




**Improved Robotic Platform to perform  
Maintenance and Upgrading Roadworks:  
The HERON Approach**

**Grant Agreement Number: 955356**

**D4.2: Motion Planning and Learning Manipulation Actions  
(version 1)**

<b>Work package</b>	WP4: Motion and High-Level Planner for the automated HERON system
<b>Activity</b>	Task 4.2 “Online Motion planning” and Task 4.3 “Learning manipulation actions
<b>Deliverable</b>	D4.2: Motion Planning and Learning Manipulation Actions (version 1)
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## Document Control Sheet

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0.3	13/03/2023	Initial draft of manipulation skills	Nikhilesh Alatur
0.4	20/03/2023	Introduction, remaining parts.	Nikhilesh Alatur, Olov Andersson
0.5	27/03/2023	Complete draft for internal review	Nikhilesh Alatur, Olov Andersson
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