




Improved Robotic Platform to perform Maintenance and Upgrading Roadworks: The HERON Approach

Grant Agreement Number: 955356

D5.3: Design and Development of the Robotic Platform with adaptive and enhanced capabilities

Work package	WP5: Development of the Robotic Platform, Improved Navigation and integration with the sensing devices.
Activity	Task 5.3. Adaptation of the HERON Robotic Platform
Deliverable	D5.3: Design and Development of the Robotic Platform with adaptive and enhanced capabilities.
Authors	Raquel Julia (ROB), Miquel Cantero (ROB)
Status	Final (F)
Version	1.3
Dissemination Level	Confidential (CO)
Document date	27/05/2024
Delivery due date	31/03/2024
Actual delivery date	27/05/2024
Internal Reviewers	Franziska Schmidt (UGE), Christos Polykretis (SATWAYS)
	This project has received funding from the European Union’s Horizon 2020 Research and Innovation Programme under grant agreement no 955356.

Document Control Sheet

Version history table			
Version	Date	Modification reason	Modifier
0.0	20/02/2024	Initial table of contents	ROB
0.1	21/02/2024	Introduction and video guide per use-case	ROB
1.0	25/04/2024	Updated videos and information	ROB
1.1	30/04/2024	Corrections from STWS review	ROB, STWS
1.2	30/04/2024	Corrections from UGE	ROB, UGE
1.3	24/05/2024	Final version	ROB

Legal Disclaimer

This document reflects only the views of the author(s). The European Commission is not in any way responsible for any use that may be made of the information it contains. The information in this document is provided “as is”, and no guarantee or warranty is given that the information is fit for any particular purpose. The above referenced consortium members shall have no liability for damages of any kind including without limitation direct, special, indirect, or consequential damages that may result from the use of these materials subject to any liability which is mandatory due to applicable law. © 2024 by HERON Consortium.